# Position-Dependent mass FGH 

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#### Abstract

In what follows we are going to adapt the Fourier Grid Hamiltonian Method to be applied to potentials with position-dependent masses.


## 1 Introduction

The Fourier-grid Hamiltonian method use a mixed position and momentum representation to describe the Hamiltonian to be applied to Schrödinger's equation.

$$
\begin{equation*}
\hat{H}=\hat{T}+V(\hat{x}) \tag{1}
\end{equation*}
$$

where $\hat{T}$ is the kinetic energy operator and $V(\hat{x})$ is the potential energy operator. That Hamiltonian still was not put on a specific representation.

In the coordinate representation, the basis is such that

$$
\begin{equation*}
\hat{x}|x\rangle=x|x\rangle \tag{2}
\end{equation*}
$$

where vectors $|x\rangle$ forms an orthonormal basis

$$
\begin{equation*}
\left\langle x_{s} \mid x_{j}\right\rangle=\frac{\delta_{s j}}{\Delta x} . \tag{3}
\end{equation*}
$$

The completeness relationship is

$$
\begin{equation*}
\sum_{s}\left|x_{s}\right\rangle \Delta x\left\langle x_{s}\right|=1 \tag{4}
\end{equation*}
$$

As we know in position representation potential operator is diagonal

$$
\begin{equation*}
\left\langle x_{s}\right| V(\hat{x})\left|x_{j}\right\rangle=V\left(x_{s}\right) \frac{\delta_{s j}}{\Delta x} . \tag{5}
\end{equation*}
$$

The momentum representation is given by the state vectors $|k\rangle$, and the momentum operator is diagonal in such a representation

$$
\begin{equation*}
\hat{p}|k\rangle=\hbar k|k\rangle . \tag{6}
\end{equation*}
$$

When the potential representing the system has a position-dependent mass, the Hamiltonian becomes non-hermitian. In order to rescue the hermiticity, an usual approach is to symmetrize it, by writing the kinetic energy operator as

$$
\begin{equation*}
\hat{K}=\frac{1}{2} \hat{p}\left[\frac{1}{m(\hat{x})}\right] \hat{p} \tag{7}
\end{equation*}
$$

The kinetic operator element of matrix becomes

$$
\begin{equation*}
\hat{K}_{s j}=\left\langle x_{s}\right| \hat{K}\left|x_{j}\right\rangle . \tag{8}
\end{equation*}
$$

Using the completeness relationship for the momentum representation

$$
\begin{equation*}
\sum_{q}\left|k_{q}\right\rangle \Delta k\left\langle k_{q}\right|=1 \tag{9}
\end{equation*}
$$

and the one for the position representation (eq. 4),

$$
\begin{gather*}
\hat{K}_{s j}=\frac{1}{2}\left\langle x_{s}\right|\left[\hat{p} \sum_{l=-n}^{n}\left|k_{l}\right\rangle \Delta k\left\langle k_{l}\right|\left[\frac{1}{m(\hat{x})}\right] \hat{p} \sum_{q=-n}^{n}\left|k_{q}\right\rangle \Delta k\left\langle k_{q}\right|\right]\left|x_{j}\right\rangle .  \tag{10}\\
\hat{K}_{s j}=\frac{1}{2}\left\langle x_{s}\right|\left[\hat{p} \sum_{l=-n}^{n}\left|k_{l}\right\rangle \Delta k\left\langle k_{l}\right| \sum_{r=1}^{N} \frac{1}{m(\hat{x})}\left|x_{r}\right\rangle \Delta x\left\langle x_{r}\right| \hat{p} \sum_{q=-n}^{n}\left|k_{q}\right\rangle \Delta k\left\langle k_{q}\right|\right]\left|x_{j}\right\rangle . \tag{11}
\end{gather*}
$$

Rearranging the sums and applying the operators,

$$
\begin{equation*}
\hat{K}_{s j}=\frac{1}{2} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{q=-n}^{n}\left\langle x_{s}\right|\left[\hbar k_{l}\left|k_{l}\right\rangle \Delta k\left\langle k_{l}\right| \frac{1}{m_{r}}\left|x_{r}\right\rangle \Delta x\left\langle x_{r}\right| \hbar k_{q}\left|k_{q}\right\rangle \Delta k\left\langle k_{q}\right|\right]\left|x_{j}\right\rangle, \tag{12}
\end{equation*}
$$

where $m_{r}=m\left(x_{r}\right)$.

$$
\begin{gather*}
\hat{K}_{s j}=\frac{1}{2} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{q=-n}^{n} \hbar k_{l}\left\langle x_{s} \mid k_{l}\right\rangle \Delta k m_{r}^{-1}\left\langle k_{l} \mid x_{r}\right\rangle \Delta x \hbar k_{q}\left\langle x_{r} \mid k_{q}\right\rangle \Delta k\left\langle k_{q} \mid x_{j}\right\rangle,  \tag{13}\\
\hat{K}_{s j}=\frac{1}{2} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{q=-n}^{n} p_{l} p_{q} \Delta k^{2}\left\langle x_{s} \mid k_{l}\right\rangle m_{r}^{-1}\left\langle k_{l} \mid x_{r}\right\rangle\left\langle x_{r} \mid k_{q}\right\rangle\left\langle k_{q} \mid x_{j}\right\rangle \Delta x, \tag{14}
\end{gather*}
$$

where $p_{i}=\hbar k_{i}=\hbar i \Delta k=2 \pi i \hbar / N \Delta x$. The transformation between representations is given by the fourier transform

$$
\begin{equation*}
\langle k \mid x\rangle=\frac{1}{\sqrt{2 \pi}} e^{-i k x} \tag{15}
\end{equation*}
$$

Therefore

$$
\begin{gather*}
\hat{K}_{s j}=\frac{1}{2} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{q=-n}^{n} \frac{p_{l} p_{q}}{m_{r}} \Delta k^{2} \frac{e^{i k_{l} x_{s}}}{\sqrt{2 \pi}} \frac{e^{-i k_{l} x_{r}}}{\sqrt{2 \pi}} \frac{e^{i k_{q} x_{r}}}{\sqrt{2 \pi}} \frac{e^{-i k_{q} x_{j}}}{\sqrt{2 \pi}} \Delta x,  \tag{16}\\
\hat{K}_{s j}=\frac{1}{2} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{q=-n}^{n} \frac{p_{l} p_{q}}{m_{r}} \Delta k^{2} \frac{e^{i k_{l}\left(x_{s}-x_{r}\right)}}{2 \pi} \frac{e^{i k_{q}\left(x_{r}-x_{j}\right)}}{2 \pi} \Delta x, \tag{17}
\end{gather*}
$$

For an equally space mesh $x_{i}=i \Delta x$, and $k_{i}=i \delta k$,

$$
\begin{equation*}
\hat{K}_{s j}=\frac{1}{2} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{q=-n}^{n} \frac{p_{l} p_{q}}{m_{r}} \Delta k^{2} \frac{e^{i l \Delta k(s-r) \Delta x}}{2 \pi} \frac{e^{i q \delta k(r-j) \Delta x}}{2 \pi} \Delta x, \tag{18}
\end{equation*}
$$

Writing $\Delta k=2 \pi / N \Delta x$, we get

$$
\begin{equation*}
\hat{K}_{s j}=\frac{1}{2 N^{2} \Delta x} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{q=-n}^{n} \frac{p_{l} p_{q}}{m_{r}} e^{2 \pi i \frac{l(s-r)}{N}} e^{2 \pi i \frac{q(r-j)}{N}} . \tag{19}
\end{equation*}
$$

Note that for each element of matrix we have to proceed three sums, which is quite expensive computationally. Let's try to group some terms. As we see, $l$ and $q$ sums are almost the same, lets examine some terms. For instance, considering $l=q$,

$$
\begin{equation*}
\hat{K}_{s j}^{l=q}=\frac{1}{2 N^{2} \Delta x} \sum_{r=1}^{N} m_{r}^{-1} \sum_{l=-n}^{n} p_{l}^{2} e^{2 \pi i \frac{l(s-j)}{N}} . \tag{20}
\end{equation*}
$$

The sum of the mass, if its constant returns the total mass $\sum_{r=1}^{N} m_{r}^{-1}=$ $N / m$, so

$$
\begin{equation*}
\hat{K}_{s j}^{l=q}=\frac{1}{N \Delta x} \sum_{l=-n}^{n} \frac{p_{l}^{2}}{2 m} e^{2 \pi i \frac{l(s-j)}{N}}, \tag{21}
\end{equation*}
$$

recovering traditional Kinetic energy element of matrix.
Considering now superior $t^{t h}$ diagonal, by setting $l=q+t$,

$$
\begin{gather*}
\hat{K}_{s j}^{q=l-t}=\frac{1}{2 N^{2} \Delta x} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{t=l+n}^{l-n} \frac{p_{l} p_{l-t}}{m_{r}} e^{2 \pi i \frac{l(s-r)}{N}} e^{2 \pi i \frac{(l-t)(r-j)}{N}} .  \tag{22}\\
\hat{K}_{s j}^{q=l-t}=\frac{1}{2 N^{2} \Delta x} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{t=l+n}^{l-n} \frac{p_{l} p_{l-t}}{m_{r}} \exp \left[2 \pi i \frac{(l(s-j)+t(j-r))}{N}\right] .  \tag{23}\\
\hat{K}_{s j}^{q=l-t}=\frac{1}{2 N^{2} \Delta x} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{t=l+n}^{l-n} \frac{p_{l} p_{l-t}}{m_{r}} \exp \left[2 \pi i \frac{l(s-j)}{N}\right] \exp \left[2 \pi i \frac{t(j-r)}{N}\right] . \tag{24}
\end{gather*}
$$



$$
\begin{equation*}
\hat{K}_{s j}^{q=l-t}=\frac{1}{2 N^{2} \Delta x} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{t=l-n}^{l+n} \frac{p_{l} p_{l-t}}{m_{r}} \exp \left[2 \pi i \frac{l(s-j)}{N}\right] \exp \left[-2 \pi i \frac{t(j-r)}{N}\right] . \tag{25}
\end{equation*}
$$

Suppose a determined $n$, the second sum has three terms $-n \leq l \leq n$, and the third sum runs $l-n \leq t \leq l+n$, with a total of $2 n+1$ terms for each $l$.

Being $[2 \pi i(s-j) / N]=\beta$, and $[-2 \pi i(j-r) / N]=\alpha$, we get

$$
\begin{equation*}
\hat{K}_{s j}^{q=l-t}=\frac{1}{2 N^{2} \Delta x} \sum_{r=1}^{N} \sum_{l=-n}^{n} \sum_{t=l-n}^{l+n} \frac{p_{l} p_{l-t}}{m_{r}} e^{\beta l} e^{\alpha t} \tag{26}
\end{equation*}
$$

As shown in table 1 , for $n=3$, the sum over t runs from -6 to 6 , depending on the $l$. We can use the indexes in the table to explicitly expand the product of the sums.

Rewriting only the second and third sums, for the sake of simplicity, assuming $n=1$ (using the indexes highlighted with the box in the table 1)

$$
\begin{align*}
& \sum_{l=-1}^{1} \sum_{t=l-1}^{l+1} e^{\beta l} e^{\alpha t}=p_{-1} e^{-\beta}\left[p_{1} e^{-2 \alpha}+p_{0} e^{-1 \alpha}+p_{-1} e^{0 \alpha}\right]+ \\
& \quad p_{0} e^{0 \beta}\left[p_{1} e^{-1 \alpha}+p_{0} e^{0 \alpha}+p_{-1} e^{1 \alpha}\right]+p_{1} e^{1 \beta}\left[p_{1} e^{0 \alpha}+p_{0} e^{1 \alpha}+p_{-1} e^{2 \alpha}\right] .  \tag{27}\\
& \sum_{l=-1}^{1} \sum_{t=l-1}^{l+1} e^{\beta l} e^{\alpha t}=\operatorname{tr}\left[\begin{array}{ccc}
p_{-1} e^{-\beta} & p_{-1} e^{-\beta} & p_{-1} e^{-\beta} \\
p_{0} e^{0 \beta} & p_{0} e^{0 \beta} & p_{0} e^{0 \beta} \\
p_{1} e^{\beta} & p_{1} e^{\beta} & p_{1} e^{\beta}
\end{array}\right]\left[\begin{array}{ccc}
p_{1} e^{-2 \alpha} & p_{1} e^{-\alpha} & p_{1} e^{0 \alpha} \\
p_{0} e^{-\alpha} & p_{0} e^{0 \alpha} & p_{0} e^{\alpha} \\
p_{-1} e^{0 \alpha} & p_{-1} e^{\alpha} & p_{-1} e^{2 \alpha}
\end{array}\right] \tag{28}
\end{align*}
$$

Therefore, the double sum could be recast as the trace of the product of two relatively simple matrices

$$
\begin{equation*}
\sum_{l=-1}^{1} \sum_{t=l-1}^{l+1} e^{\beta l} e^{\alpha t}=\operatorname{tr}(\hat{A} \cdot \hat{B}) . \tag{29}
\end{equation*}
$$

Backing to the kinetic energy operator element of matrix,

$$
\begin{equation*}
\hat{K}_{s j}=\frac{1}{2 N^{2} \Delta x} \sum_{r} \frac{1}{m_{r}} \operatorname{tr}\left(\hat{A}_{s, j, r} \cdot \hat{B}_{s, j, r}\right) \tag{30}
\end{equation*}
$$

Now we can rewrite the Hamiltonian element of matrix

$$
\begin{equation*}
\hat{H}_{s j}=\frac{1}{2 N^{2} \Delta x} \sum_{r=1}^{N} \frac{1}{m_{r}} \operatorname{tr}\left(\hat{A}_{s, j, r} \cdot \hat{B}_{s, j, r}\right)+V\left(x_{s}\right) \frac{\delta_{s j}}{\Delta x} . \tag{31}
\end{equation*}
$$

